## JVC

## SERVICE MANUAL

## CD RECEIVER

## KD-LX330R/KD-LX110R



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## Safety precaution

\. CAUTION Burrs formed during molding may be left over on some parts of the chassis. Therefore, pay attention to such burrs in the case of preforming repair of this system.

〔 CAUTION Please use enough caution not to see the beam directly or touch it in case of an adjustment or operation check.

## Preventing static electricity

## 1.Grounding to prevent damage by static electricity

Electrostatic discharge (ESD), which occurs when static electricity stored in the body, fabric, etc. is discharged, can destroy the laser diode in the traverse unit (optical pickup). Take care to prevent this when performing repairs.
2.About the earth processing for the destruction prevention by static electricity

Static electricity in the work area can destroy the optical pickup (laser diode) in devices such as CD players.
Be careful to use proper grounding in the area where repairs are being performed.

## 2-1 Ground the workbench

Ground the workbench by laying conductive material (such as a conductive sheet) or an iron plate over it before placing the traverse unit (optical pickup) on it.

## 2-2 Ground yourself

Use an anti-static wrist strap to release any static electricity built up in your body.


## 3. Handling the optical pickup

1. In order to maintain quality during transport and before installation, both sides of the laser diode on the replacement optical pickup are shorted. After replacement, return the shorted parts to their original condition. (Refer to the text.)
2. Do not use a tester to check the condition of the laser diode in the optical pickup. The tester's internal power source can easily destroy the laser diode.

## 4.Handling the traverse unit (optical pickup)

1. Do not subject the traverse unit (optical pickup) to strong shocks, as it is a sensitive, complex unit.
2. Cut off the shorted part of the flexible cable using nippers, etc. after replacing the optical pickup. For specific details, refer to the replacement procedure in the text. Remove the anti-static pin when replacing the traverse unit. Be careful not to take too long a time when attaching it to the connector.
3. Handle the flexible cable carefully as it may break when subjected to strong force.
4. It is not possible to adjust the semi-fixed resistor that adjusts the laser power. Do not turn it

## Attention when traverse unit is decomposed

*Please refer to "Disassembly method" in the text for pick-up and how to detach the substrate.
1.Solder is put up before the card wire is removed from connector on the CD substrate as shown in Figure.
(When the wire is removed without putting up solder, the CD pick-up assembly might destroy.)
2.Please remove solder after connecting the card wire with when you install picking up in the substrate.


## Disassembly method <Main body> <br> Removing the top chassis

(See Fig. 1 to 5)

1. Remove the two screws $\mathbf{A}$ attaching the bottom cover to the top chassis on the bottom of the body.
2. Remove the two screws $\mathbf{B}$ attaching the top chassis on both sides of the body.
3. Remove the two screws $\mathbf{C}$ and the two screw $\mathbf{D}$ attaching the heat sink on the left side of the body.
4. Remove the two screws $\mathbf{E}$ and the screw $\mathbf{F}$ on the back of the body.
5. Remove the two screws $\mathbf{G}$ on the upper side of the body.
6. Move the top chassis upward and disconnect the CD mechanism connector from the main board connector by pulling it. Remove the top chassis from the body.


Fig.4-1 (KD-LX300)


Fig.4-2 (KD-LX100)


Fig. 1


Fig. 2


Fig. 3


Fig. 5

## Removing the front panel assembly

 (See Fig. 6 to 8)- Prior to performing the following procedure, remove the top chassis assembly.

1. Disconnect the flexible harness from connector CN701 on the main board assembly.
2. Remove the four screws $\mathbf{H}$ attaching the front panel assembly on both sides of the body. Remove the front panel toward the front.


Fig.6-1 (KD-LX300)


Fig.6-2 (KD-LX100)


Fig. 7

## Removing the Front Board (See Fig.9)

- Prior to performing the following procedure, remove the top chassis assembly and the front panel assembly.

1. Remove the four screws I attaching the front board on the back of the front panel assembly and release the eight joints a.


Fig. 8


Fig. 9

Removing the lifter unit (See Fig.10)

- Prior to performing the following procedure, remove the top chassis assembly and the front panel assembly.

1. Disconnect the harness from connector CN503and CN504 on the main board.
2. Remove the four screws $\mathbf{J}$ and detach the lifter unit from the bottom cover.

## Removing the feed motor (L) (See Fig.11)

- Prior to performing the following procedure, remove the lifter unit.

1. Remove the washer attaching the clutch assembly and detach the clutch assembly from the shaft of the lifter unit.
2. Remove the two screws $\mathbf{K}$ attaching the feed motor (L).

## ■Removing the feed motor (R) (See Fig.12)

- Prior to performing the following procedure, remove the lifter unit.

1. Remove the washer attaching the clutch assembly and detach the clutch assembly from the shaft of the lifter unit.
2. Remove the two screws $\mathbf{L}$ attaching the feed motor (R).


Fig. 12


Fig.10-1 (KD-LX300)


Fig.10-2 (KD-LX100)


Fig. 11

## Removing the operation assembly

(See Fig. 13 to 17)

- Prior to performing the following procedure, remove the top chassis assembly, the front panel assembly and the lifer unit.

1. Disconnect the card wire from connector CN702 on the main board and remove the operation assembly.
2. Remove the three screws $\mathbf{M}$ attaching the right and left brackets which fix gears on both sides of the operation assembly.
3. Remove the springs 5 and 6 from the operation assembly.

ATTENTION: When reassembling, correctly engage the switch S651 and S652 on the main board and the right gear with the part $\mathbf{b}$ of the operation assembly.


Fig. 13


Fig. 14


Fig. 16


Fig. 15

- Prior to performing the following procedure, remove the operation assembly.

1. Remove the six screws $\mathbf{N}$ attaching the button panel on the operation assembly.
2. Pull out the operation switch board from inside of the button panel.


Fig. 17


Fig. 18

Removing the CD mechanism assembly
(See Fig.19)

- Prior to performing the following procedure, remove the top chassis.

1. Remove the three screws $\mathbf{O}$ and the $C D$ mechanism assembly from the top chassis.


Fig. 19

## Removing the main board assembly

(See Fig. 20 to 22)

- Prior to performing the following procedure, remove the top chassis.

1. Disconnect the flexible harness from connector CN701, the card wire from CN702 on the main board and the harness from CN503 and CN504 respectively.
2. Remove the three screws $\mathbf{P}$ attaching the main board assembly to the bottom cover on the upper side of the body.
3. Move the main board in the direction of the arrow and release the three joints c. (At this point, the main board can be removed with the rear panel and the rear heat sink.)
4. Remove the three screws $\mathbf{Q}$ attaching the rear heat sink on the back of the body.
5. Remove the two screws $\mathbf{R}$ and the screw $\mathbf{S}$ attaching the rear panel. Now, the main board assembly will be removed.

ATTENTION: When reassembling, correctly engage the switch S651 and S652 on the main board and the right gear with the part $\mathbf{b}$ of the operation assembly (Refer to Fig.21).


Fig.22-1 (KD-LX300)


Fig.22-2 (KD-LX100)


Fig.20-1 (KD-LX300)


Fig.20-2 (KD-LX100)


Fig. 21

## <CD mechanism section>

## $\square$ Removing the CD mechanism control board (See Fig. 1 and 2)

1. Remove the screw $\mathbf{A}$ and the pickup cover attached to the front bracket with the double-sided tapes.
2. Unsolder the three parts $\mathbf{a}, \mathbf{b}$ and $\mathbf{c}$ on the $C D$ mechanism control board.
3. Remove the stator fixing the CD mechanism control board and the damper bracket (To remove the stator smoothly, pick up the center part).
4. Remove the screw $\mathbf{B}$ attaching the $C D$ mechanism control board.
5. Remove the CD mechanism control board in the direction of the arrow while releasing it from the two damper bracket slots $\mathbf{d}$ and the front bracket slot $\mathbf{e}$.
6. Disconnect the flexible wire from connector on the pickup unit.

> ATTENTION: Turn the FD gear in the direction of the arrow to move the entire pickup unit to the appropriate position where the flexible wire of the CD mechanism unit can be disconnected easily (Refer to Fig.2).


Fig. 1


Fig. 2


Fig. 3


Fig. 4


Fig. 5

## ■ Removing the CD mechanism assembly

 (See Fig.1, 6 to 9)- Prior to performing the following procedure, remove the CD mechanism control board and the front bracket (loading motor).

1. Remove the three screws $\mathbf{E}$ and the damper bracket.
2. Raise the both sides fix arms and move the fix plates in the direction of the arrow to place the four shafts $\mathbf{g}$ as shown in Fig. 8 and 9.
3. Remove the CD mechanism assembly and the two springs $\mathbf{h}$ attaching the flame.
4. Remove the two screws $\mathbf{F}$ and both sides rear damper brackets from the dampers. Detach the CD mechanism assembly from the left side to the right side.

ATTENTION: The CD mechanism assembly can be removed if only the rear damper bracket on the left side is removed.


Fig. 7


Fig. 8


Fig. 9

## Removing the feed motor assmbly

(See Fig.10)

- Prior to performing the following procedure, remove the $C D$ mechanism control board, the front bracket (loading motor) and the CD mechanism assembly.

1. Remove the two screws $\mathbf{G}$ and the feed motor assembly.


Fig. 10

## ■Removing the pickup unit

(See Fig. 10 and 11)

- Prior to performing the following procedure, remove the CD mechanism control board, the front bracket (loading motor), the CD mechanism assembly and the feed motor assembly.

1. Detach the FD gear part of the pickup unit upward. Then remove the pickup unit while pulling out the part j of the FD screw.

ATTENTION: When reattaching the pickup unit, reattach the part $\mathbf{i}$ of the pickup unit, then the part $j$ of the FD screw.


Fig. 11
2. Remove the screw $\mathbf{H}$ attaching the nut push spring plate and the pickup mount nut from the pickup unit. Pull out the FD screw.

## Removing the spindle motor

(See Fig. 12 and 13)

- Prior to performing the following procedure, remove the CD mechanism control board, the front bracket (loading motor), the CD mechanism assembly and


Fig. 12 the feed motor assembly.

1. Turn up the CD mechanism assembly and remove the two springs $\mathbf{k}$ on both sides of the clamper arms. Open the clamper arm upward.
2. Turn the turn table and remove the two screws I and the spindle motor.


Fig. 13

## Adjustment method

$\square$ Test instruments required for adjustment

1. Digital oscilloscope ( 100 MHz )
2. AM Standard signal generator
3. FM Standard signal generator
4. Stereo modulator
5. Electric voltmeter
6. Digital tester
7. Tracking offset meter
8. Test Disc JVC :CTS-1000
9. Extension cable for check EXTGS004-26P $\times 1$

■ Standard volume position
Balance and Bass \&Treble volume : Indication"0"
Loudness: OFF
BBE : OFF
Frequency Band
■ FM $87.5 \mathrm{MHz} \sim 108.0 \mathrm{MHz}$
MW 144 ~ $279 \mathrm{kHz}, 520 \mathrm{kHz}$ ~ 1620 kHz

- Dummy load

Exclusive dummy load should be used for AM, and FM. For FM dummy load,there is a loss of 6 dB between SSG output and antenna input.The loss of 6 dB need not be considered since direct reading of figures are applied in this working standard.

Power supply voltage DC14.4V (10.5~16V)
Load impedance 20Kohm(2 Speakers connection)
Output Level Line out 2.0V (Vol. MAX)

■How to connect the extension cable for adjusting


## Extension cord connecting method

## ■ Using the extention cords to connect the front panel with the main board

Remove the main board follwing the disassembly methode. Then reattachi the heat sink to main board.

1. Using the 2pin extention cord (EXTLX001-2p), connect the harness of the feed motor ( L ) assembly with the connector CN503 on the main board.
2. Using the 2pin extention cord (EXTLX001-2p), connect the harness of the feed motor (R) assembly with the connector CN504 on the main board.
3. Using the jig board (EXTLX002-SWPWB), its installing to the chassis, then using 4pin extention cord (EXTLX002-4P) connect the harness of the lifter detecting board with the connector CN704 on the board.
4. Connect the connector (EXTLX001-6PC) and extension wire (EXTLX001-6PF), connect the 6pin connector CN702 on the main board.
5. Connect the connector (EXTLX002-16PC) and extension wire (EXTLX002-16PF), connect the 16pin connector CN701 on the main board.


## Extension cord list

EXTLX002-JIG: Kit including the following 8 extension parts.

| No. | Parts number | Quantity | Description |
| :---: | :--- | :---: | :--- |
| 1 | EXTLX001-2P | 2 | 2Pin, 30cm extension cord |
| 2 | EXTLX001-6PF | 1 | 6Pin, 30cm flat wire |
| 3 | EXTLX001-6PC | 1 | 6Pin x 2, interlocking connector |
| 4 | EXTLX002-16PF | 1 | 16Pin flat wire |
| 5 | EXTLX002-16PC | 1 | 16Pin, interlocking connector |
| 6 | EXTLX002-SWPWB | 1 | 3 switch PWB |
| 7 | EXTLX002-4P | 1 | 4Pin, 30cm extension cord |

Besides the above kit, we offer the conventional extension cord for CD mechanism which are not essential to operation check or service. The mechanism should be directly connected to the board using the extension wire. EXTGS004-26P


## Functions of the mechanism under the service mode

With the three error modes stored in maximum in the internal memory of the mechanism in the body of this system, it is posible under the service mode to call the contents of error according to the following steps when any error has occurred.
Press the three buttons (UP button $\underset{1}{ })+\left(4^{\circ}\right.$ button) $+($ Func button $\bumpeq$ mes $)$. Then it is possible to select the follwing service modes. After changing over to the service mode, press the UP button and DOWN button $1-4$ to change the mode. For executing the respective service modes, press the SEL button.
With the service mode 2 , it is possible to call the error codes of the mechanism.


Data stored in EEPROM

1. RDS data
2. CD mechanism error cord
3. Station name (to be input by user)
4. DISC name (to be input by user)
5. AUX input name
*Any data 3 to 5 above should not be deleted.


## 1. Display of mechanism error

| Occurrence condition | Description | Error codes |
| :--- | :--- | :---: |
| Disc loading error | 1. SW4 is not turned off. <br> 2. SW3 is not turned on. | 090011 |
| 090013 |  |  |
| Eject error | 1. SW\# is not turned off. | 010021 |
| Error during standby for loading | 1. In case SW2 has been positioned to "L" before <br> starting loading during waiting for 15sec. | 800031 |

## 2. Display of CD error

| Occurrence condition | Description | Error codes |
| :--- | :--- | :---: |
| Pickup feeding error <br> 1. Inner peripheral feeding error <br> (10sec.) | The pickup cannot returned to the inner <br> 2. Outer peripheral feeding error <br> (10sec.) | Thpheral, and the REST switch is not turned off. <br> The perup cannot be returned to the outer <br> peripheral, and the REST switch is not turned off. |
| Focus search error <br> In the case of focusing error after <br> 3-way focus searching | In case the focus cannot be searched by one set <br> of focus searching (3-way focus searching) after <br> disc change and focus shock, judge that the focus <br> searching system is in error. | 80051 |
| Tracking balance adjusting error <br> In the case of time-over (1sec.) <br> of timer | In case tracking balance cannot be adjusted even <br> after elapse of 1sec. following execution of the <br> adjusting command (TBA). | 820053 |
| TOC area searching error <br> In the case of time-over (10sec.) <br> of timer <br> Reading error <br> IN the case of time-over (30sec.) <br> of timer | In case TOC area searching is not ended even after <br> elapse of 10sec. <br> In case reading is not ended even after elapse of 30 <br> sec. during TOC reading action. | 820055 |
| 1st tracking access error <br> In the case of time-over (10sec.) <br> of timer | In case the first tracking access is not ended even <br> after elapse of 10sec. following completion of TOC <br> reading. | 800059 |
| Last tracking access error <br> In the case of time-over (10sec.) <br> of timer | In case the last tracking access is not ended even <br> after elapse of 10sec. following completion of first <br> tracking under the RUNNING mode. | 800060 |
| Q code reading error <br> In the case of time-over (0.6sec.) <br> of timer | In case the Q code cannot be read for 0.6sec. <br> during playing TOC program area. | 800062 |
| TEXT data reading error | In case all TEXT data cannot be read. | 800063 |

## Flow of functional operation until TOC read



Feed Section

-Focus Section


## Spindle Section



## Tracking Section



## Maintenance of laser pickup

(1) Cleaning the pick up lens

Before you replace the pick up, please try to clean the lens with a alcohol soaked cotton swab.
(2) Life of the laser diode

When the life of the laser diode has expired, the following symptoms will appear.
(1) The level of RF output (EFM output:ampli tude of eye pattern) will be low.


## Replacement of laser pickup

(3) Semi-fixed resistor on the APC PC board The semi-fixed resistor on the APC printed circuit board which is attached to the pickup is used to adjust the laser power.Since this adjustment should be performed to match the characteristics of the whole optical block, do not touch the semi-fixed resistor. If the laser power is lower than the specified value,the laser diode is almost worn out, and the laser pickup should be replaced. If the semi-fixed resistor is adjusted while the pickup is functioning normally, the laser pickup may be damaged due to excessive current.

Turn off the power switch and,disconnect the power cord from the ac outlet.


Plug the power cord in, and turn the power on. At this time,check that the laser emits for about 3seconds and the objective lens moves up and down.
Note: Do not observe the laser beam directly.


## Description of major ICs

FAN8037 (IC661) : CD driver

1. Pin layout \& Block diagram

2. Pin function

| Pin <br> No. | Symbol | I/O | Function | Pin | Nymbol | I/O | Function |
| :---: | :---: | :---: | :--- | :--- | :--- | :--- | :--- |
| 1 | IN2 + | I | CH2 op-amp input(+) | 25 | DO7+ | O | CH7 drive output(+) |
| 2 | IN2-- | I | CH2 op-amp input((-) | 26 | DO6- | O | CH6 drive output(-) |
| 3 | OUT2 | O | CH2 op-amp output | 27 | DO6+ | O | CH6 drive output(+) |
| 4 | IN3+ | I | CH3 op-amp input(+) | 28 | PGND2 | - | Power ground2 |
| 5 | IN3- | I | Ch3 op-amp input(-) | 29 | DO5- | O | CH5 drive output(-) |
| 6 | OUT3 | O | CH3 op-amp output | 30 | DO5+ | O | CH5 drive output(+) |
| 7 | IN4+ | I | CH4 op-amp input(+) | 31 | DO4- | O | CH4 drive output(-) |
| 8 | IN4- | I | CH4 op-amp input( $(-)$ | 32 | DO4+ | O | CH4 drive output(+) |
| 9 | OUT4 | O | CH4 op-amp output(+) | 33 | DO3- | O | CH3 drive output(-) |
| 10 | CTL1 | I | CH5 motor speed control | 34 | DO3+ | O | CH3 drive output(+) |
| 11 | FWD1 | I | CH5 forward input | 35 | PGND1 | - | Power ground1 |
| 12 | REV1 | I | CH5 reverse input | 36 | DO2- | O | CH2 drive output(-) |
| 13 | CTL2 | I | CH6 motor speed control | 37 | DO2+ | O | CH2 drive output(+) |
| 14 | FWD2 | I | CH6 forward input | 38 | DO1- | O | CH1 drive output(-) |
| 15 | REV2 | I | CH6 reverse input | 39 | DO1+ | O | CH1 drive output(+) |
| 16 | SGND | - | Signal ground | 40 | PVCC1 | - | Power supply voltage |
| 17 | FWD3 | I | CH7 forward input | 41 | REGOX | I | Regulator feedback input |
| 18 | REV3 | I | CH7 reverse input | 42 | REGX | O | Regulator output |
| 19 | CTL3 | I | CH7 motor speed control | 43 | RESX | I | Regulator reset input |
| 20 | SB | I | Stand by | 44 | VREF | I | Bias voltage input |
| 21 | PS | I | Power save | 45 | SVCC | - | Signal supply voltage |
| 22 | MUTE | I | All mute | 46 | IN1+ | I | CH1 op-amp input(+) |
| 23 | PVCC2 | - | Power supply voltage | 47 | IN1- | I | CH1 op-amp input(-) |
| 24 | DO7- | O | CH7 drive output( $(-)$ | 48 | OUT1 | O | CH1 op-amp output |

## KD-LX330R/KD-LX110R

## UPD784215AGC-128 (IC701) : UNIT CPU

1.Terminal Layout

| 75 | $\sim$ | 51 |
| :---: | :---: | ---: |
| 76 |  | 50 |
| 2 |  | 2 |
| 100 |  | 26 |
| 1 | $\sim$ | 25 |

2.Pin Function (1/2)

| Pin No. | Symbol | I/O | Function |
| :---: | :---: | :---: | :---: |
| 1 | SW2 | 1 | Detection switch of CD mechanism |
| 2 | SW3 | 1 | Detection switch of CD mechanism |
| 3 | SW4 | 1 | Detection switch of CD mechanism |
| 4 | REST-SW | 1 | Reset signal input from CD mechanism |
| 5 | LM0 | O | Loading motor control signal output |
| 6 | LM1 | O | Loading motor control signal output |
| 7 | DIMMER-OUT | O | Dimmer signal output |
| 8 | LCD-PWR | O | LCD driver power supply control output H:ON |
| 9 | VDD | - | Power supply terminal |
| 10 | X2 | - | Connecting the crystal oscillator for system main clock |
| 11 | X1 | - | Connecting the crystal oscillator for system main clock |
| 12 | VSS | - | Power supply terminal |
| 13 | XT2 | - | Connecting the crystal oscillator for system sub clock |
| 14 | XT1 | - | Connecting the crystal oscillator for system sub clock |
| 15 | RESET | I | System reset signal input |
| 16 | SW1 | I | Detection switch of CD mechanism |
| 17 | BUS-INT | 1 | Cut-in input for J-BUS signal |
| 18 | PS2 | I | Power save 2, Working together back up by H input, to stop mode |
| 19 | CRUISE | 1 | Pulse signal input port for Cruise control |
| 20 | NC | - | Clock signal input for RDS |
| 21 | NC | - | RDS data input |
| 22 | REMOCON | I | Remote control signal input |
| 23 | AVDD | - | Power supply terminal |
| 24 | AVREF0 | - | Power supply terminal |
| 25 | VOL1 | 1 | Input for rotation volume detection pulse judgment to relation V1 |
| 26 | VOL2 | 1 | Input for rotation volume detection pulse judgment to relation V2 |
| 27 | KEY0 | 1 | Key control signal input 0 |
| 28 | KEY1 | I | Key control signal input 1 |
| 29 | KEY2 | I | Key control signal input 2 |
| 30 | LEVEL | 1 | Signal input port of level meter |
| 31 | NC | 1 | Non connect |
| 32 | S.METER | I | S.Meter level input |
| 33 | AVSS | - | Connect to GND |
| 34 | W-VOL | O | Subwoofer volume control analogue output |
| 35 | DOT-CONT | O | Dot contrast signal output |
| 36 | AVREF | - | Power supply terminal |
| 37 | BUS-SI | 1 | J-BUS data input |
| 38 | BUS-SO | O | J-BUS data output |
| 39 | BUS-SCK | I/O | J-BUS Clock signal I/O |
| 40 | STAGE2 | 1 | Initial setting |
| 41 | LCD-DA | O | Data output to LCD driver |
| 42 | LCDCL | O | Clock output to LCD driver |

Pin Function (2/2)

| Pin No. | Symbol | I/O | Function |
| :---: | :---: | :---: | :---: |
| 43 | LCD-CE1 | 0 | Chip enable output to LCD driver |
| 44 | BUZZER | 0 | BUZZER control signal output |
| 45 | E2PR-DA-I | 1 | Data input terminal from EEPROM |
| 46 | E2PR-DA-O | 0 | Data output terminal for EEPROM |
| 47 | E2PR-CLK | 0 | Clock signal I/O terminal with EEPROM |
| 48 | BUS-I/O | I/O | J-BUS I/O signal terminal |
| 49 | TM0 | 0 | Tray motor negative signal output terminal |
| 50 | TM1 | 0 | Tray motor positive signal output terminal |
| 51 | DM0 | 0 | Door motor negative signal output terminal |
| 52 | DM1 | 0 | Door motor positive signal output terminal |
| 53 | SD/ST | 1 | Station detector, Stereo signal input, H:Find Station L:Stereo |
| 54 | LOCAL | 0 | Local ON/OFF select signal output terminal |
| 55 | MONO | 0 | Monaural ON/OFF selecting output, H:MONO ON |
| 56~60 | CA-SW1~5 | 1 | DOOR/TRAY open close detect switch signal input terminal |
| 61,62 | NC | - | Non connect |
| 63 | SEEK/STOP | 0 | Auto seek/stop selecting output, H:Seek L:Stop |
| 64 | NC | - | Non connect |
| 65 | FM/AM | 0 | Selecting output for FM/AM, L:FM H:AM |
| 66 | PLL-CE | 0 | CE output for IC control for PLL |
| 67 | PLL-DA | 0 | Data output for IC control for PLL |
| 68 | PLL-CK | 0 | Clock output for IC control for PLL |
| 69 | BAND IN | 1 | AM detect signal input |
| 70 | NC | - | Non connect |
| 71 | AMP KILL | - | Non connect |
| 72 | VSS | - | Connect to GND |
| 73 | DIMMER-IN | 1 | DIMMER signal input terminal |
| 74 | PS1 | 1 | Power supply terminal |
| 75 | POWER | 0 | Selecting output for power ON/OFF, H:power ON |
| 76 | CD-ON | 0 | Power supply control signal for CD H:CD |
| 77 | MUTE | 0 | MUTE output, L:MUTE ON |
| 78 | W-LPF1 | 0 | Subwoofer cut off frequency output 1 |
| 79 | W-LPF2 | 0 | Subwoofer cut off frequency output 2 |
| 80 | W-MUTE | 0 | MUTE output for Subwoofer |
| 81 | VDD | - | Power supply terminal |
| 82 | VO-DA | 0 | Data output terminal |
| 83 | VOL-CLK | 0 | Clock signal output terminal |
| 84 | NC | - | Non connect |
| 85 | GVSW | 0 | AGC/FE/TE amp gain change terminal |
| 86 | LCDRST | 0 | LCD reset signal output terminal |
| 87 | LCD-CE2 | 0 | Chip enable 2 output terminal for LCD driver |
| 88 | DMK | 0 | Motor speed control signal output terminal |
| 89 | TMK | 0 | Tray motor control signal output terminal |
| 90 | NC | - | Non connect |
| 91 | BUCK | 0 | Micon interface clock output terminal |
| 92 | CCE | 0 | Command and data sending/receiving chip enable signal output |
| 93 | RST | 0 | Reset signal output terminal reset at "L" level |
| 94 | TEST | - | Connect to GND |
| 95~98 | BUSO~3 | I/O | Micon interface data input/output terminal |
| 99 | DISC SEL | 1 | Initial setting |
| 100 | NC | - | Non connect |

## ■TC9490FA (IC521) : DSP

1. Pin layout \& Block diagram

2. Pin function (1/2)

| Pin No. | Symbol | I/O | Function |
| :---: | :---: | :---: | :--- |
| 1 | BCK | O | Bit clock output terminal |
| 2 | LRCK | O | L/R channel clock output terminal |
| 3 | AOUT | O | Audio data output terminal |
| 4 | DOUT | O | Digital data output terminal |
| 5 | IPF | O | Correction flag output terminal |
| 6 | VDD3 | - | Digital 3.3V power supply voltage terminal |
| 7 | Vss3 | - | Digital GND terminal |
| 8 | SBOK | O | Subcode Q data CRCC result output terminal |
| 9 | CLCK | O | Subcode P-W data read clock I/O terminal |
| 10 | DATA | O | Subcode P-W data output terminal |
| 11 | SFSY | O | Playback frame sync signal output terminal |
| 12 | SBSY | O | Subcode block sync signal output terminal |
| 13 | /HSO | O | Playback speed mode output terminal |

2. Pin function (2/2)

| Pin No. | Symbol | I/O | Function |
| :---: | :---: | :---: | :---: |
| 14 | /UHSO | 0 | Playback speed mode output terminal |
| 15 | PVDD3 | - | PLL-only 3.3V power supply voltage terminal |
| 16 | PDO | O | EFM and PLCK phase difference signal output terminal |
| 17 | TMAX | 0 | TMAX detection result output terminal |
| 18 | LPFN | 1 | Inverted input terminal for PLL LPF amp |
| 19 | LPFO | 0 | Outpuit terminal for PLL LPF amp |
| 20 | PVREF | - | PLL-only VREF terminal |
| 21 | VCOF | 0 | VCO filter terminal |
| 22 | AVss3 | - | Analog GND terminal |
| 23 | SLCO | 0 | DAC output terminal for data slice level generation |
| 24 | RFI | 1 | RF signal input terminal |
| 25 | AVDD3 | - | Analog 3.3V power supply voltage terminal |
| 26 | RFCT | 1 | RFRP signal center level input terminal |
| 27 | RFZI | 1 | RFRP signal zero-cross input terminal |
| 28 | RFRP | 1 | RF ripple signal input terminal |
| 29 | FEI | 1 | Focus error signal input terminal |
| 30 | SBAD | 1 | Sub-beam adder signal input terminal |
| 31 | TEI | 1 | Tracking error input terminal |
| 32 | TEZI | 1 | Tracking error signal zero-cross input terminal |
| 33 | FOO | 0 | Focus equalizer output terminal |
| 34 | TRO | O | Tracking equalizer output terminal |
| 35 | VREF | - | Analog reference power supply vpltage terminal |
| 36 | RFGC | O | RF amplitude adjustment control signal output terminal |
| 37 | TEBC | 0 | Tracking balance control signal output terminal |
| 38 | SEL | 0 | APC circuit ON/OFF signal output terminal |
| 39 | AVDD3 | - | Analog 3.3V power supply voltage terminal |
| 40 | FMO | 0 | Feed equalizer output terminal |
| 41 | DMO | 0 | Disc equalizer output terminal |
| 42 | Vss3 | - | Digital GND terminal |
| 43 | VDD3 | - | Digital 3.3V power supply voltage terminal |
| 44 | TESIN | 1 | Test input terminaal |
| 45 | XVss3 | - | System clock oscillator GND terminal |
| 46 | XI | 1 | System clock oscillator input terminal |
| 47 | XO | 0 | System clock oscillator output terminal |
| 48 | XVDD3 | - | System clock oscillator 3.3V power supply voltage terminal |
| 49 | DVss3 | - | DA converter GND terminal |
| 50 | RO | 0 | R-channel data forward output terminal |
| 51 | DVDD3 | - | DA converter 3.3V power supply terminal |
| 52 | DVR | - | Reference voltage terminal |
| 53 | LO | 0 | L-channel data forward output terminal |
| 54 | DVss3 | - | DA converter GND terminal |
| 55 | ZDET | 0 | 1 bit DA converter zero data detection flag output terminal |
| 56 | Vss5 | - | Microcontroller interface GND terminal |
| 57 | BUSO | I/O | Microcontroller interface data I/O terminal |
| 58 | BUS1 | I/O | Microcontroller interface data I/O terminal |
| 59 | BUS2 | I/O | Microcontroller interface data I/O terminal |
| 60 | BUS3 | I/O | Microcontroller interface data I/O terminal |
| 61 | BUCK | 1 | Microcontroller interface clock input terminal |
| 62 | /CCE | 1 | Microcontroller interface chip enable signal input terminal |
| 63 | /RST | 1 | Reset signal input terminal |
| 64 | VDD5 | - | Microcontroller interface 5V power supply terminal |

## 000874360-T (IC702) : System reset

1. Pin layout


2
2. Block diagram


## BA3220FV-X (IC301,IC401) : Driver

1. Pin layout \& Block diagram

2. Pin function

| Pin  <br> No. Symbol | Function |  |
| ---: | :---: | :--- |
| 1 | CL+ | Powe supply terminal for amp. |
| 2 | Vcc | power supply terminal. |
| 3 | INL | input terminal. |
| 4 | NFL | Negative feedback terminal. |
| 5 | FIL | Filter terminal. |
| 6 | NFR | Negative feedback terminal. |
| 7 | INR | Input terminal |
| 8 | CR+ | Power supply terminal for amp. |
| 9 | CR- | Output terminal of internal amp. |
| 10 | RGND | Rch GND terminal. |
| 11 | OUTR | Rch output terminal. |
| 12 | OUTL | Lch output terminal. |
| 13 | LGND | Lch GND terminal. |
| 14 | CL- | Output terminal of internal amp. |

## BD3860K (IC911) : E. volume

1.Terminal layout

|  | 33 | $\sim 23$ |  |
| :---: | :---: | :---: | :---: |
| 34 |  |  | 22 |
| 1 |  |  | 1 |
| 44 |  |  | 12 |
|  |  |  |  |
|  | 1 | $\sim 11$ |  |

## 2.Bockdiagram


3.Pin function

| Rin | Symbol | Function | Pin. | Symbol | Function |
| :---: | :---: | :--- | :--- | :--- | :--- |
| 1 | A2 | CH2 Input Pin A | 23 | VCA2 | CH2 High Pass VCA Output Pin |
| 2 | B2 | CH2 Input Pin B | 24 | LF2 | CH2 Low Pass Filter Setting Pin |
| 3 | C2 | CH2 Input Pin C | 25 | HF2 | CH2 High Pass Filter Setting Pin |
| 4 | D2 | CH2 Input Pin D | 26 | DET2 | CH2 High Pass Attack/Release Time Setting Pin |
| 5 | FIL | 1/2 VCC Pin | 27 | NC | Non connect |
| 6 | GND | Ground Pin | 28 | DET1 | CH1 High Pass Attack/Release Time Setting Pin |
| 7 | SI | Serial Data Receiving Pin | 29 | TIN1 | CH1 treble Input Pin |
| 8 | SC | Serial Clock Receiving Pin | 30 | BBOUT1 | CH1 BBE II Signal Output Pin |
| 9 | VCC | Power Supply Pin | 31 | MIX1 | CH1 Output MIX Amplifier Inverse Input Pin |
| 10 | OUTR2 | CH2 Rear Output Pin | 32 | VCA1 | CH1 High Pass VCA Output Pin |
| 11 | OUTF2 | CH2 Front Output Pin | 33 | LF1 | CH1 Low Pass Filter Setting Pin |
| 12 | OUTR1 | CH1 Rear Output Pin | 34 | HF1 | CH1 High Pass Filter Setting Pin |
| 13 | OUTF1 | CH1 Front Output Pin | 35 | LOUD1 | CH1 Loudness Filter Setting Pin |
| 14 | BOUT1 | CH1 Bass Filter Setting Pin | 36 | VIN1 | CH1 Main Volume Input Pin |
| 15 | BNF1 | CH1 Bass Filter Setting Pin | 37 | LOUD2 | VCH2 Loudness Filter setting Pin |
| 16 | BOUT2 | CH2 Bass Filter Setting Pin | 38 | VIN2 | CH2 Main Volume Input Pin |
| 17 | BNF2 | CH2 Bass Filter Setting Pin | 39 | SEL2 | CH2 Input Gain Output Pin |
| 18 | TNF2 | CH2 treble Filter Setting Pin | 40 | SEL1 | CH1 Input Gain output Pin |
| 19 | TNF1 | CH1 treble Filter Setting Pin | 41 | A1 | CH1 Input Pin A |
| 20 | TIN2 | CH2 treble Input Pin | 42 | B1 | CH1 Input Pin B |
| 21 | BBOUT2 | CH2 BBE II Signal Output Pin | 43 | C1 | CH1 Input Pin C |
| 22 | MIX2 | CH2 Output MIX Amplifier | 44 | D1 | CH1 Input Pin D |
|  |  | Inverse Input Pin |  |  |  |

1. Pin layout


## 2. Pin function

| Symbol | I/O | Function |
| :---: | :---: | :--- |
| VCC | - | Power supply. |
| GND | - | GND |
| A0,A1,A2 | I | No use connect to GND. |
| SCL | I | Serial clock input. |
| SDA | I/O | Serial data I/O of slave and ward address. |
| WP | I | Write protect terminal. |

3. Block diagram


## BU4066BCFV-X (IC322) : Quad analog switch

1. Pin layout \& Block diagram


## HA13164 (IC961) : Regulator

1.Terminal layout


UNIT R: $\Omega$
C:F
note1) TAB (header of IC)
3.Pin function
connected to GND

| Pin No. | Symbol | Function |
| :---: | :--- | :--- |
| 1 | EXTOUT | Output voltage is VCC-1 V when M or H level applied to CTRL pin. |
| 2 | ANTOUT | Output voltage is VCC-1 V when M or H level to CTRL pin and H level <br> to ANT-CTRL. |
| 3 | ACCIN | Connected to ACC. |
| 4 | VDDOUT | Regular 5.7V. |
| 5 | SW5VOUT | Output voltage is 5V when M or H level applies to CTRL pin. |
| 6 | COMPOUT | Output for ACC detector. |
| 7 | ANT CTRL | L:ANT output OFF, H:ANT output ON |
| 8 | VCC | Connected to VCC. |
| 9 | BATT DET | Low battery detect. |
| 10 | AUDIO OUT | Output voltage is 9V when M or H level applied to CTRL pin. |
| 11 | CTRL | L:BIAS OFF, M:BIAS ON, H:CD ON |
| 12 | CD OUT | Output voltage is 8V when H level applied to CTRL pin. |
| 13 | ILM AJ | Adjustment pin for ILM output voltage. |
| 14 | ILM OUT | Output voltage is 10V when M or H level applies to CTRL pin. |
| 15 | GND | Connected to GND. |

## KD-LX330R/KD-LX110R

LA4743K (IC941) : Power amp

3.Pin function

| Pin No. | Symbol |  |
| :---: | :--- | :--- |
| 1 | TAB | Header of IC |
| 2 | GND | Power GND |
| 3 | OUTRR- | Outpur(-) for front Rch |
| 4 | STBY | Stand by input |
| 5 | OUTRR+ | Output (+) for front Rch |
| 6 | VCC1/2 | Power input |
| 7 | OUTRF- | Output (-) for rear Rch |
| 8 | GND | Power GND |
| 9 | OUTRF+ | Output (+) for rear Rch |
| 10 | RIPPLE | Ripple filter |
| 11 | INRF | Rear Rch input |
| 12 | INRR | Front Rch input |
| 13 | SGND | Signal GND |
| 14 | INLR | Front Lch input |
| 15 | INLF | Rear Lch input |
| 16 | ONTIME | Power on time control |
| 17 | OUTLF+ | Output (+) for rear Lch |
| 18 | GND | Power GND |
| 19 | OUTLF- | Output (-) for rear Lch |
| 20 | VCC3/4 | Power input |
| 21 | OUTLR+ | Output (+) for front |
| 22 | MUTE | Muting control input |
| 23 | OUTLR- | Output (-) for front |
| 24 | GND | Power GND |
| 25 | NC | Non connection |

## LC75811W (IC602) : LCD driver

1. Pin layout

|  | 60 | $\sim$ | 41 |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 61 |  |  |  | 40 |
| 2 |  |  |  | 2 |
| 80 |  |  |  | 21 |
|  | 1 | $\sim$ | 20 |  |



| Pin No. | Symbol | I/O | Function |
| :---: | :---: | :---: | :--- |
| $1 \sim 58$ | S3~S60 | O | Segment driver output terminal |
| 59 | COM0 | O | Common driver output terminal |
| $60 \sim 65$ | COM3~COM8 | O | Common driver output terminal |
| 66 | COM1 | O | Common driver output terminal |
| 67 | VDD | - | Power supply for logic section |
| 68 | VLCD | - | Power supply for LCD driver section |
| $69 \sim 71$ | VLCD1~VLCD3 | I | LCD voltage input terminal |
| 72 | VSS | - | Connect to ground |
| 73 | OSCO | O | Oscillation output terminal |
| 74 | OSCI | I | Oscillation input terminal |
| 75 | RES | I | Reset signal input terminal |
| 76 | CE | I | Chip enable input terminal |
| 77 | CL | I | Clock signal input terminal |
| 78 | DI | I | Serial data input terminal |
| $79 \sim 80$ | S1~S2 | O | Segmrnt driver output terminal |

## ■ LC75823W (IC602) : LCD driver

1. Pin Layout \& Symbol

2. Pin Function

| Pin No. | Symbol | I/O | Function |
| :---: | :---: | :---: | :---: |
| 1 to 52 | S1 to S52 | O | Segment output pins used to display data transferred by serial data input. |
| 53 to 55 | COM1 to COM3 | 0 | Common driver output pins. The frame frequency is given by : $\mathrm{t} 0=(\mathrm{fosc} / 384) \mathrm{Hz}$. |
| 56 | VDD | -- | Power supply connection. Provide a voltage of between 4.5 and 6.0 V . |
| 57 | $\overline{\text { INH }}$ | 1 | Display turning off input pin. <br> TNT="L" (Vss) ----- off (S1 to S52, COM1 to COM3="L" <br> INT="H" (VDD)----- on <br> Serial data can be transferred in display off mode. |
| 58 | VDD1 | 1 | Used for applying the LCD drive $2 / 3$ bias voltage externally. <br> Must be connected to VDD2 when a $1 / 2$ bias drive scheme is used. |
| 59 | VDD2 | 1 | Used for applying the LCD drive $1 / 3$ bias voltage externally. <br> Must be connected to VDD1 when a $1 / 2$ bias drive scheme is used. |
| 60 | Vss | -- | Power supply connection. Connect to GND. |
| 61 | OSC | I/O | Oscillator connection. <br> An oscillator circuit is formed by connecting an external resistor and capacitor at this pin. |
| 62 63 | CE CL | 1 | Serial data <br> interface connection <br> to the controller. CE : Chip enable |
| 64 | DI |  | DI : Transfer data |

■ NJM2904M (IC951) : Dual ope amp

1. Pin layout


## ■ NJM4565MD (IC323,IC960) : Ope amp

1. Pin layout \& Block diagram


## RPM6938-SV4 (IC603) : Remote censor

1.Block diagram


## M5282FP-XE (IC321) : E. volume

1. Pin layout

2. Block diagram

3. Pin function

| Pin <br> No. | Symbol | Function |
| :---: | :---: | :--- |
| 1 | Vcc/2 | Vcc/2 output for microphone amp. |
| 2 | Amp+IN | Microphone amp. positive input terminal. |
| 3 | Amp-IN | Microphone amp. negative input terminal. |
| 4 | Amp OUT | Microphone amp. output terminal. |
| 5 | GND | Ground. |
| 6 | NC | Non connection. |
| 7 | VCA IN | VCA input terminal. |
| 8 | Vc | VCA control terminal. |
| 9 | VCA OUT | VCA output terminal. |
| 10 | Vcc | Power supply. |

## KD-LX330R/KD-LX110R

TA2147F-X (IC601) : Head amp

2. Pin function

| Pin No. | Symbol | I/O | Function |
| :---: | :---: | :---: | :--- |
| 1 | Vcc | - | 3.3V power supply terminal |
| 2 | FIN | I | Main-beam amp input terminal |
| 3 | FPI | I | Main-beam amp input terminal |
| 4 | TPI | I | Sub-beam amp input terminal |
| 5 | TNI | I | Sub-beam amp input terminal |
| 6 | MDI | I | Monitor photo diode amp input terminal |
| 7 | LDO | O | Laser diode amp output terminal |
| 8 | SEL | I | APC circuit ON/OFF control signmal, laser diode (LDO) control signal input or <br> bottom/peak detection frequency change terminal |
| 9 | TEBC | I | Tracking error balance adjustment signal input terminal |
| 10 | TEN | I | Tracking error signal generation amp negative-phase input terminal |
| 11 | TEO | O | Tracking error signal generation amp output terminal |
| 12 | RFDC | O | RF signal peak detection output terminal |
| 13 | GVSW | I | AGC/FE/TE amp gain change terminal |
| 14 | VRO | O | Reference voltage (VRO) output terminal |
| 15 | FEO | O | Focus error signal generation amp output terminal |
| 16 | FEN | I | Focus error signal generation amp negative-phase input terminal |
| 17 | RFRP | O | Signal amp output pin for track count |
| 18 | RFRPIN | I | Signal generation amp input terminal for track count |
| 19 | RFGO | O | RF signal amplitude adjustment amp output terminal |
| 20 | RFGC | I | RF amplitude adjustment control signal input terminal |
| 21 | AGCIN | I | RF signal amplitude adjustment amp input terminal |
| 22 | RFO | O | RF signal generation amp output terminal |
| 23 | RFN | I | RF signal generation amp input terminal |
| 24 | GND | - | GND terminal |

1. Pin layout

2. Block diagram


## TB2118F-X (IC21) : PLL


3.Pin Function

| Pin <br> No. | Symbol | I/O | Function | Pin <br> No. | Symbol | I/O | Function |
| ---: | :---: | :---: | :--- | :--- | :--- | :--- | :--- |
| 1 | XOUT | O | Crystal oscillator pin | 13 | IFC | I | IF signal input |
| 2 | OSC | - | Non connect | 14 | VDD | - | Power pins for digital block |
| 3 | CE | I | Chip enable input | 15 | FMIN | I | FM band local signal input |
| 4 | DI | I | Serial data input | 16 | AMIN | I | AM band local signal input |
| 5 | CK | I | Clock input | 17 | DGND | - | Connect to GND (for digital circuit) |
| 6 | DOUT | O | Serial data output | 18 | FMCP | O | Charge pump output for FM |
| 7 | SR | O | Register control pin | 19 | VT | - | Tuning voltage biased to 2.5V. |
| 8 | I/01 | I/O | I/O ports | 20 | AMCP | O | Charge pump output for AM |
| 9 | I/02 | I/O | I/O ports | 21 | VCC | - | Power pins for analog block |
| 10 | OUT1 | - | Non connect | 22 | RF | I | Ripple filter connecting pin |
| 11 | OUT2 | - | Non connect | 23 | AGND | - | Connect to GND (for analog circuit) |
| 12 | VDD2 | - | Single power supply for REF. frequency block | 24 | XIN | I | Crystal oscillator pin |

■ HD74HC126FP (IC771) : Changer control


■ NJM2100M (IC821) : Operation amp

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